



Introduction

- We propose a deep learning framework that allows learning parametric implicit shape models, using shape priors together with appearance
- Objective of segmenting low-quality images or datasets:
- Low signal-to-noise ratio
- Limited amount of training data
- Missing parts
- Occlusion of parts

Approach

- Model receives an image and outputs a segmentation or image reconstruction
- We use a parametric Disjunctive Normal Shape Model (DSNM) [1] together with deep learning:
 - A CNN produces image features
 - Last FC layer outputs parameters of the implicit shape model (each 2D half-space needs 3 coefficients to be reconstructed: Ax+By+C>0)
 - Subsets (groups) of half-spaces create polytopes from their intersection
 - Union of polytopes creates final shape
- Half-spaces are relaxed to logistic functions to make the model differentiable
- Training uses MSE as loss, comparing the output of the network to an image ground truth (we do not use shape parameters as ground truth)



Image Segmentation by Deep Learning of Disjunctive Normal Shape Model Shape Representation /> Mehran Javanmardi¹, **Ricardo Bigolin Lanfredi¹**, Mujdat Cetin², Tolga Tasdizen¹

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Experiments

- We used models with 2 convolutional layers, 2 fully connected layers, 24 polytopes and 8 half-spaces per polytope.
- We use Dice coefficients to report results.

Aircraft Dataset [2]

- 11 binary images of aircrafts
- Test images have noise in two different levels and occlusion of left wing
- We trained the model in a leave-one-out setting

	Kim et	Erdil et	Propose
	al. [2]	al. [3]	approad
Image 1, low noise	91.12	94.49	94.23
Image 2, low noise	92.69	94.75	98.51
Image 3, low noise	89.97	94.66	96.96
Image 1, high noise	87.15	89.86	94.80
Image 2, high noise	90.31	93.25	98.14
Image 3, high noise	88.03	90.05	97.83







Walking Silhouettes dataset [4]

• 30 images selected – 16 for training Images have high level of additive white noise

	Kim et al. [2]	Erdil et al. [3]	Proposed approach
Image 1	87.13	88.10	91.38
Image 2	89.87	89.87	93.30
Image 3	85.43	86.58	92.06

Dendritic Spine Dataset [5]					
 We trained two shape models, one for mushroom spines and one for stubby spines 					
 88 mushroom spines and 27 stubby spines 					
 We trained models using 8 examples of each 					
Foulonneau	Kim et al.	Chen et	Erdil et al. [8] with	Erdil et al. [8] with	Proposed
et al. [6]	[2]	al. [7]	geometric priors	appearance priors	approach
73.48	64.24	72.38	74.74	74.92	75.25

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MNIST dataset [9]



Conclusion

- for deliberate initialization

References

- N. Ramesh et al. Disjunctive normal shape models. ISBI 2015 [2] J. Kim et al. Nonparametric shape priors for active contour-based image segmentation. Sig. Proc., 87, 2007 [3] E. Erdil et al. Mcmc shape sampling for image segmentation with nonparametric shape priors CVPR 2016 [4] D. Cremers et al. Kernel density estimation and intrinsic alignment for shape priors in level set segmentation. IJCV 2006. [5] Obtained from Neuronal Structure and Foundation Laboratory of Champalimaud Neuroscience Foundation in Lisbon [6] A. Foulonneau et al. Multi-reference shape priors for active contours. IJCV 2009. [7] S. Chen et al. Level set segmentation with both shape and intensity priors. ICCV 2009.
- [8] E. Erdil et al. Nonparametric joint shape and feature priors for image segmentation. IEEE Trans. on Im. Proc., 2017. [9] Y. LeCun et al. Gradient-based learning applied to document recognition. Proc. of the IEEE, 1998.

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Output



Model predicts 10 different shapes and 10 class probabilities • Model outputs the shape corresponding to the class with highest probability • We added Gaussian noise and occlusions/exclusion of parts to test set

st image	Output	Ground truth	Test image	Output	Test image	Output
1		l	1			l
2	2	2	2	2	2	2
B	3	3	3	ŝ	3	3
И	4	4	31	4	#	4
5	5	5	55	5	5	F
6	6	6	1.	6	*	6
X	7	7		٦	4	٦
8	8	8	27	8	8	8
4	9	c_1	41	9	9	9

• Our framework of CNN+DSNM was able to segment data with noise, with occlusion/removal of parts and with limited amount of training data • We achieved superior scores against previous methods in 3 datasets • The model is computationally efficient and fully automated, with no need